

RAPID UPDATE ON OPTICAL SIM + BEZIER TRACKS

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1. OPTICAL SIMULATIONS

PVS: Library Mode

- This service has now subsumed the old “PhotonLibraryService”, and handles all lookup based optical simulation methods
- As such these methods are now available to both simulation and reconstruction algorithms.
- This represents a MAJOR overhaul of the library building and sampling since the last talk

```
void SetVisibilityModel(int model) { fVisModel = model; }
int GetVisibilityModel()          { return fVisModel; }

double GetQuenchingFactor(double dQdx);

double DistanceToOpDet(          double* xyz, unsigned int OpChannel );
double SolidAngleFactor(         double* xyz, unsigned int OpChannel );
double GetVisibility(            double* xyz, unsigned int OpChannel );

std::vector<double> GetAllVisibilities( double* xyz );

void StoreLibrary();

void StoreLightProd(    int VoxID, double N );
void RetrieveLightProd( int& VoxID, double& N );

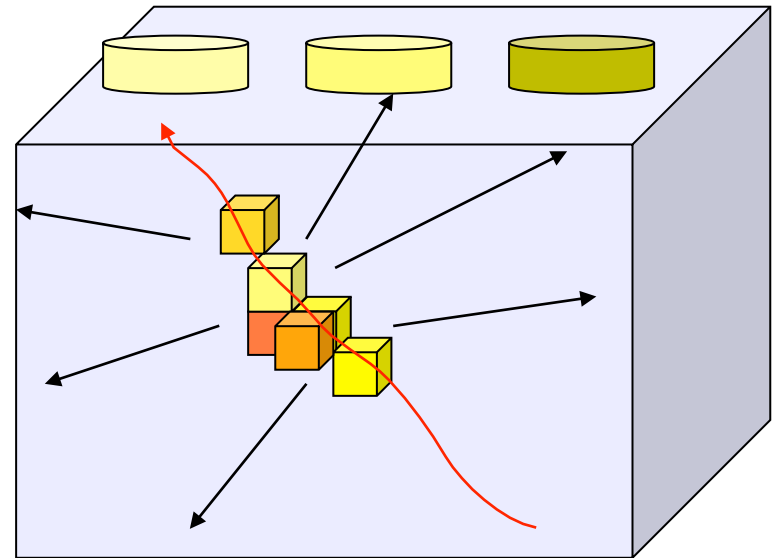
void SetLibraryEntry(    int VoxID, int OpChannel, double N);
double GetLibraryEntry( int VoxID, int OpChannel);

bool IsBuildJob() { return fLibraryBuildJob; }

sim::PhotonVoxelDef GetVoxelDef() {return fVoxelDef; }
```

Library Building

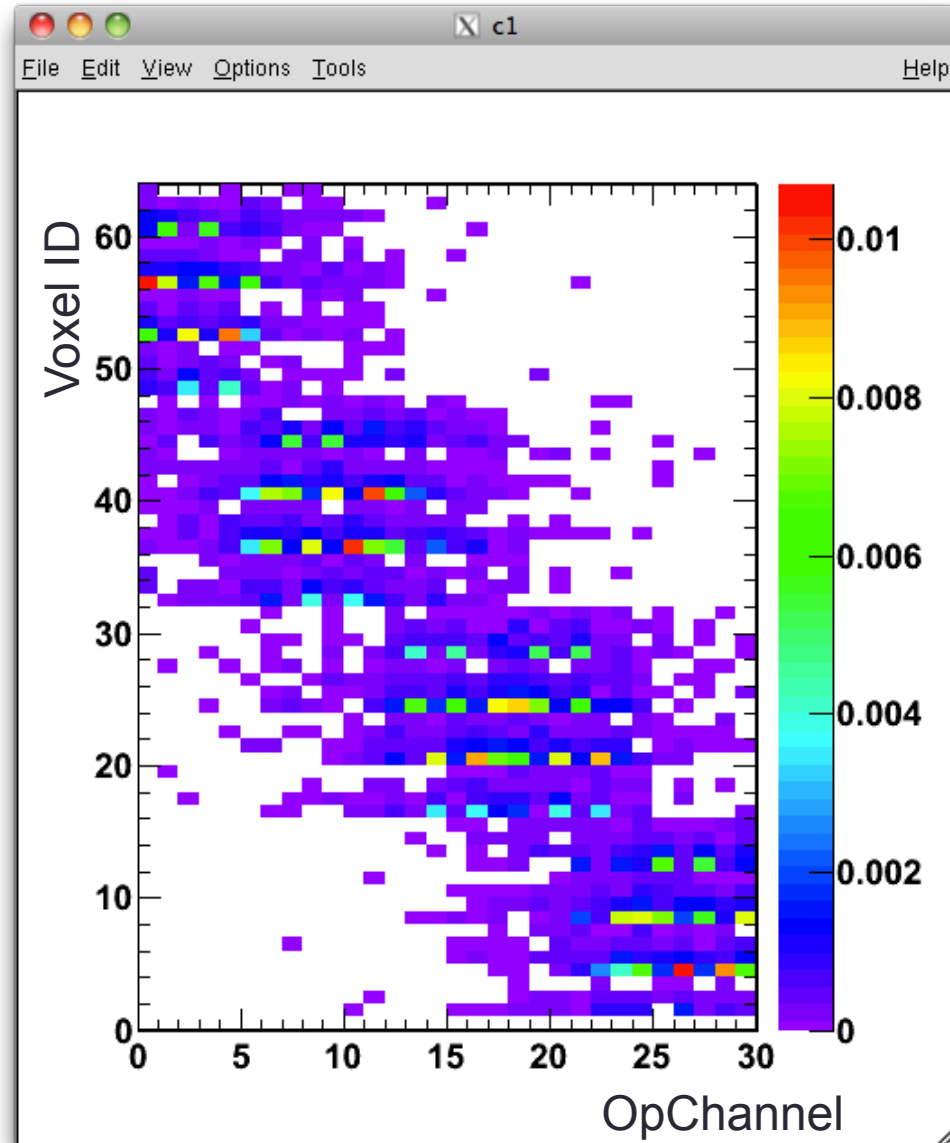
- Enable service PhotonVisibilityService
 - Specify in its configuration:
 - *BuildLibrary : true*
 - *Number of voxels in x,y,z*
 - *Optional : sub-region of detector to simulate*
- Run modules LightSource, LArG4, SimPhotonCounter
- Brightness should be specified for LightSource. Other than this, PhotonVisibilityService will configure the modules appropriately.
- Library file is output through the TFileService

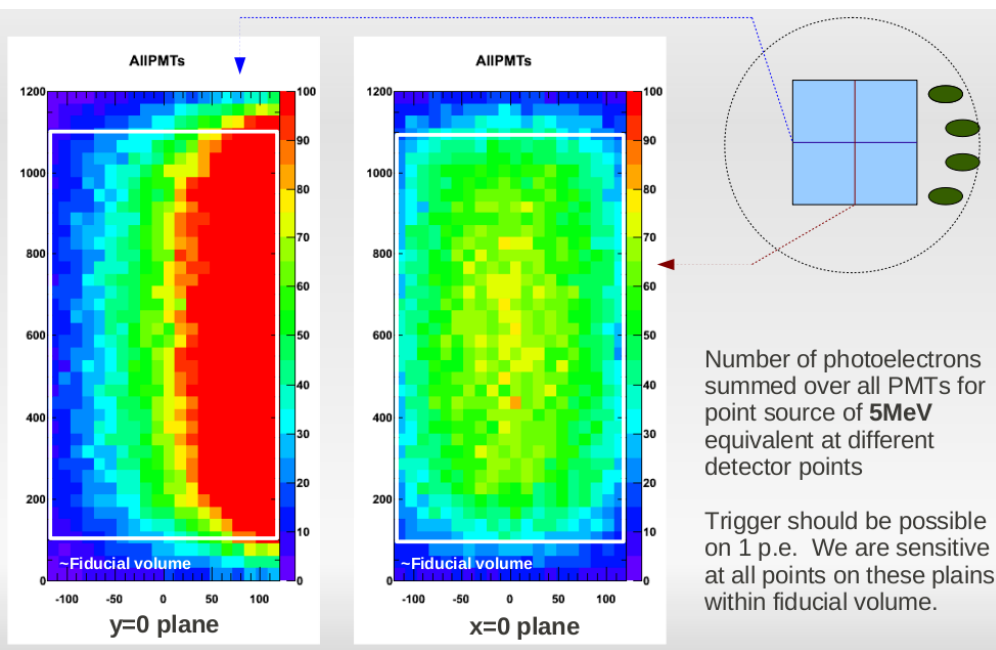


Library Build Test Run

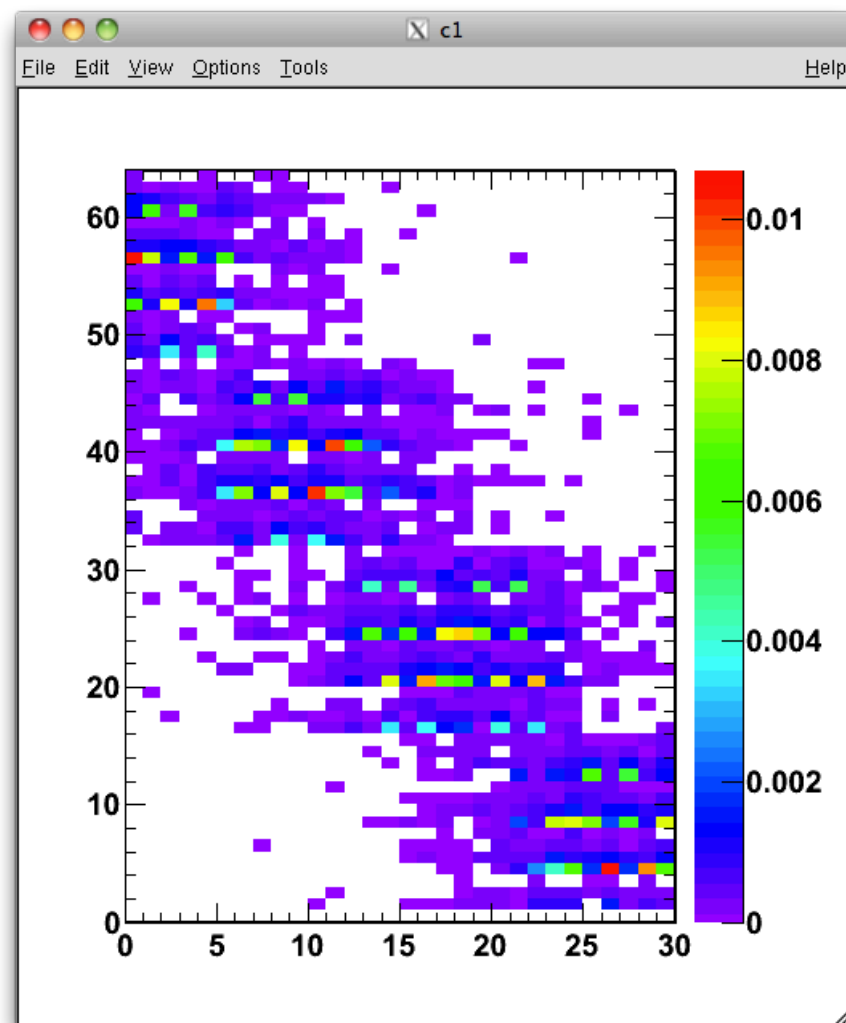
- Quick test run : 4x4x4 voxels, 10,000 photons in each
- Library build job takes about 10 mins

Colors show fraction of photons detected





Effectively the same information, but broken down per PMT and in a weird coordinate system.



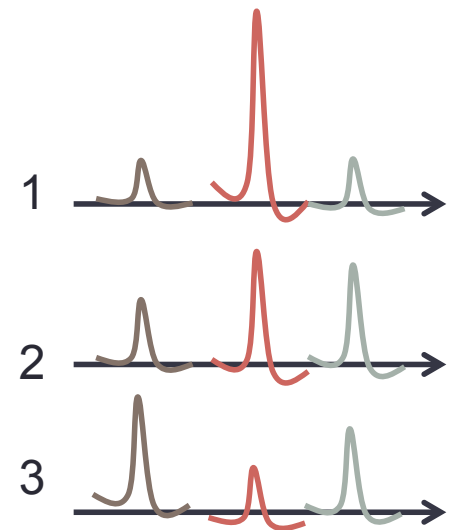
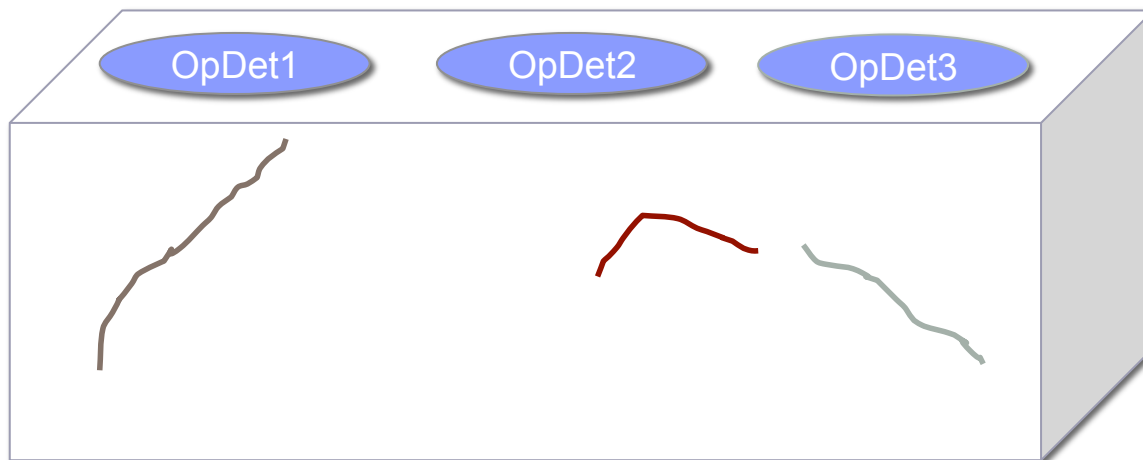
Library sampling simulation tool coming online soon (most code exist in uncommitted form).

Scaling Up to Grid Job

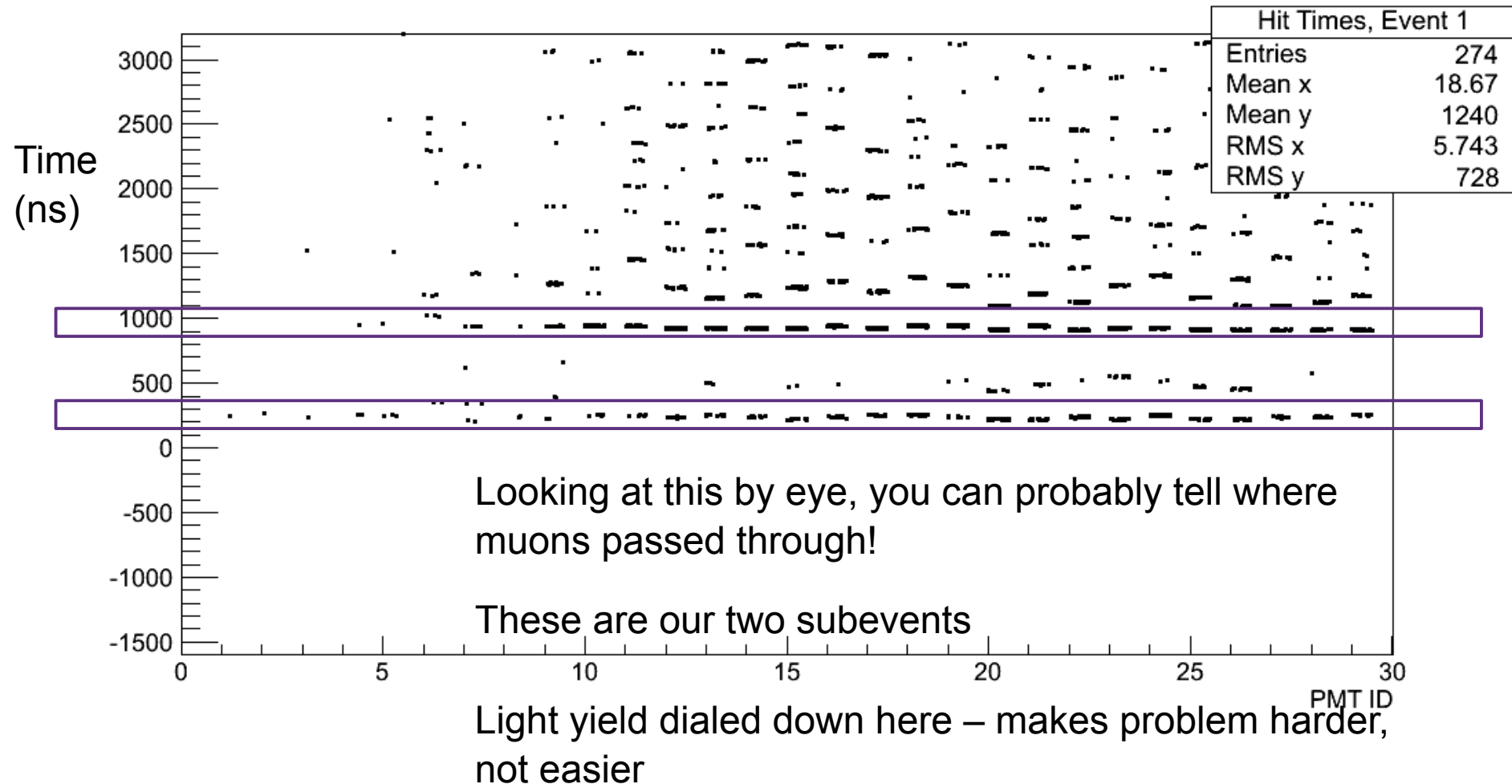
- Need to get started building full MicroBooNE library using grid jobs.
- Do a few voxels in each and then combine library library files offline.
- Feasible library size for MicroBooNE light collection:
 - 25 x 25 x 100, 100,000 photons / vox ~ 10 x 10 x 10 cm voxels
- Scaling up, this is about 1600 hours of grid jobs.
- These numbers not optimized, and there may be room for increasing efficiency by disabling irrelevant physics in LArG4.

Geometrical T0 Finding

- **1: Find subevents by matching large PMT signals in time**
- **2: Make hypotheses of relative amount of light per PMT for each track**
- 3: Likelihood fit to match track to light hypothesis, and find T0.



Optical Subevent Finding



The algorithm

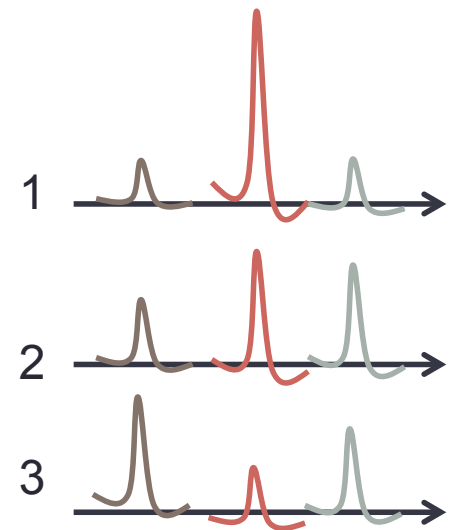
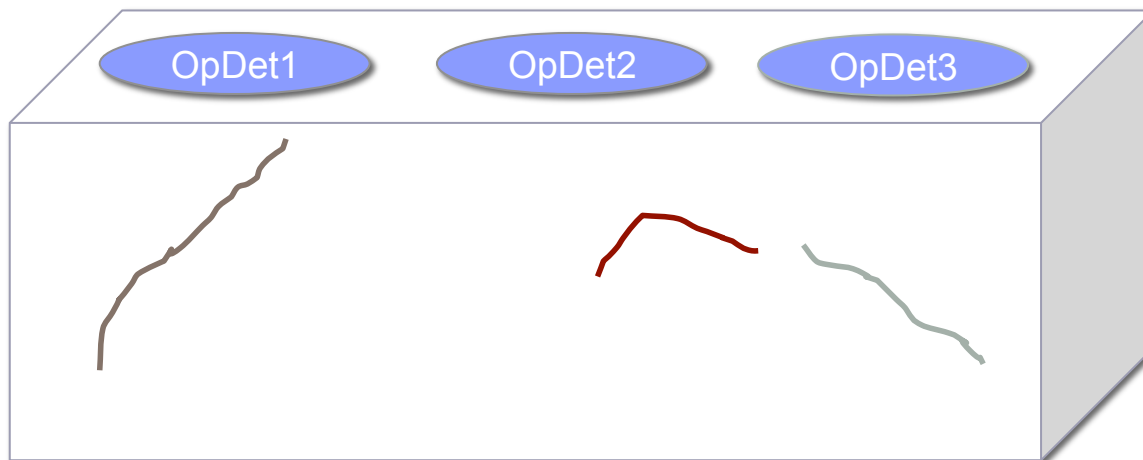
- 1) Compute average # & standard deviation of PE in peaks for each PMT
 - - We will only consider peaks larger than (avg – 1 stdev)
- 2) Find the largest peak
- 3) Scan through all peaks and find ones that fit in time with this largest peak
 - - Each peak can be in *at most* one subevent
- 4) Find the next largest peak not in a subevent, and repeat until all peaks have been sorted
- 5) Merge subevents that are very close in time and have completely disjoint sets of PMTs listed
 - - Each subevent has at most 1 peak from any given PMT

Accuracy

- Finds correct number of subevents for:
 - Up to 6 particles (muons), sometimes 7
 - Particle separation times > 180 ns
 - At smaller separation times, peaks merge
 - All these particles are traveling straight through detector volume (seen by most PMTs)
- Subevent timing fluctuates by about 100 ns (if we run same event multiple times)
 - Fit parameters waver slightly
- Now waiting on fast sim to be ready in order to test efficiency over different event classes – update next meeting

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Geometrical T0 Finding

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Part 2 ready to go – but ideally need library to be built to lookup visibility.

An undergrad, Deana Del Vecchio is going to help us assess the accuracy of using just $1/r^2$ and solid angle to determine visibility

2. BEZIER TRACKS

Bezier Tracks – Module to Algorithm

- 1. Bezier tracker now updated to adhere to the algorithm / module scheme, like seeds, spacepoints etc.
- This partially so that bezier tracks can be used in interactive event display for handscan

Bezier Tracks - Calorimetry

- Bezier track now has a method to produce an `anab::Calorimetry` object.
- `anab::Calorimetry` modified to allow pitches for curved tracks, so one pitch per point. Previous constructors / interfaces are left unchanged for compatability.
- Pitch corrected dE/dx measurement in a given view, along curved track generated in `BezierTrack` method, not external calorimetry module, using Andrzej's new "`calo::CalorimetryAlg`"
- Also interfaces with Mitches event display mode

[root](#) / [trunk](#) / [TrackFinder](#) / [BezierTrack.h](#)

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```
anab::Calorimetry GetCalorimetryObject(std::vector<art::Ptr<recob::Hit> > Hits, geo::View_t view);
```


Bezier Tracks – Input modes

- Tracking module now has four modes:
 - 1) Run using pre-generated seeds
 - 2) Run iteratively on unstructured hit collection
 - 3) Single shot run 2D on cluster combinations
 - 4) Iterative run on 2D cluster combinations (not tested)